

**Exercise 1. Linear sigma model**

The linear sigma model consists of two Dirac fermions that we arrange in a vector  $\psi = \begin{pmatrix} u \\ d \end{pmatrix}$  and four real scalars  $\tilde{\sigma}$  and  $\vec{\pi} = (\pi^1, \pi^2, \pi^3)$  described by the Lagrangian density

$$\mathcal{L}_\sigma^{\text{lin}} = \frac{1}{2}(\partial_\mu \tilde{\sigma})(\partial^\mu \tilde{\sigma}) + \frac{1}{2}(\partial_\mu \vec{\pi}) \cdot (\partial^\mu \vec{\pi}) - \frac{\lambda}{4}(\tilde{\sigma}^2 + \vec{\pi} \cdot \vec{\pi} - v^2)^2 + \bar{\psi} i \not{\partial} \psi + g \bar{\psi}(\tilde{\sigma} + i \vec{\sigma} \cdot \vec{\pi} \gamma_5) \psi. \quad (1)$$

(a) Show that (1) can be recast as

$$\mathcal{L}_\sigma^{\text{lin}} = \frac{1}{4} \text{tr} (\partial_\mu \Sigma)^\dagger (\partial^\mu \Sigma) - \frac{\lambda}{4} \left[ \frac{1}{2} \text{tr} \Sigma^\dagger \Sigma - v^2 \right]^2 + \bar{\psi}_L i \not{\partial} \psi_L + \bar{\psi}_R i \not{\partial} \psi_R + g \bar{\psi}_L \Sigma \psi_R + g \bar{\psi}_R \Sigma^\dagger \psi_L \quad (2)$$

where  $\Sigma \equiv \tilde{\sigma} \mathbb{1} + i \vec{\sigma} \cdot \vec{\pi}$  and  $\psi_{R,L}$  are the right-handed and left-handed parts.

The fields  $\psi_{R,L}$  and  $\Sigma$  transform according to

$$\psi_{R,L} \rightarrow U_{L,R} \psi_{R,L}, \quad \Sigma \rightarrow U_L \Sigma U_R^\dagger, \quad U_{R,L} \equiv \exp \left( -\frac{1}{2} \vec{\alpha}_{R,L} \cdot \vec{\sigma} \right) \in \text{SU}(2). \quad (3)$$

(b) Using the properties of the Pauli matrices, recover  $\tilde{\sigma}$  and  $\vec{\pi}$  from  $\Sigma$  and deduce their transformation properties.

**Exercise 2. Non-linear sigma model**

(a) Using the properties of the Pauli matrices, prove that

$$U \equiv \exp \left( i \frac{\vec{\sigma} \cdot \vec{\xi}}{v} \right) = \cos \left( \frac{\xi}{v} \right) + i \frac{\vec{\sigma} \cdot \vec{\xi}}{\xi} \sin \left( \frac{\xi}{v} \right), \quad \xi = |\vec{\xi}|. \quad (4)$$

The Lagrangian of the non-linear sigma model contains the term

$$\mathcal{L}_\sigma^{\text{non-lin}} \supset \Delta \mathcal{L} = \frac{1}{4} (v + S)^2 \text{tr} (\partial_\mu U)^\dagger (\partial^\mu U). \quad (5)$$

(b) Using (4), express  $\Delta \mathcal{L}$  from  $S$  and  $\vec{\xi}$  retaining only the terms up to  $\mathcal{O}(1/v)$ .

*Hint.* You might find the following relation useful:  $\partial_\mu \xi = (\vec{\xi} \cdot \partial_\mu \vec{\xi}) / \xi$ .

(c) What kind of vertices do these term represent?