

# Introduction to Integrability

Lecture Slides, Chapter 4

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## 4. Spectral Curves

### 4.1 Spectral Curve

Start with some generic state  $\vec{S}; (t) \rightarrow T(\omega)$  Lax matrix  
 know spectrum of  $T(\omega)$ , in particular trace  $F(\omega)$  is conserved

Eigenvalues spectrum of  $T(\omega)$  is time-independent,  
 for all  $\omega \in \mathbb{C}$ .

here trace  $F(\omega)$  determines spectrum

$$\text{recall } \det L_j(\omega) = 1 + \frac{1}{\omega^2} \Rightarrow \det T(\omega) = \left(1 + \frac{1}{\omega^2}\right)^L$$

$F(\omega) = \ln T(\omega)$  is a polynomial of deg.  $L$  in  $1/\omega$

$$\begin{aligned} \tilde{\tau}_1 \tilde{\tau}_2 &= \det T^{-1} \\ \tilde{\tau}_1 + \tilde{\tau}_2 &= \ln \overline{T} = F \end{aligned} \Rightarrow \tau_{1,2}(\omega) = \frac{1}{2} F(\omega) \pm \sqrt{\frac{1}{4} F(\omega)^2 - \left(1 + \frac{1}{\omega^2}\right)^L}$$

## Singularities

$$\tilde{U} = 0$$

elements of  $\tau_{1,2}$  is polynomial in  $1/U$  of degree  $L \Rightarrow$  analytic except at  $L$ -fold pole at  $U = \tilde{U} = 0 \Rightarrow \tau_{1,2}(U)$  will have  $L$ -fold pole at  $U = 0$ .

nevertheless  $\tau_{1,2}(U)$  do not need to be analytical at  $U \neq 0$   
some exceptions to analyticity possible due to solving EV.

Name where radicand of soln of  $\tau_{1,2}$  equals zero.

$\Rightarrow$  square-root branch points  $\hat{U}_j$  where  $\frac{1}{4} F(\hat{U}_j)^2 = \left(1 + \frac{1}{\hat{U}_j^2}\right)^L$

algebraic eq. of deg  $2L$  in  $1/\hat{U}_j \Rightarrow 2L$  solutions  $\hat{U}_j$   $j=1..2L$ .

These are where  $\tau_1(\hat{U}_j) = \tau_2(\hat{U}_j)$

Note that  $F(\omega)$  is special at  $\omega = \infty$

$$F(\omega) = 2 + \frac{D}{\omega} - \frac{1}{\omega^2} (\omega^2 - L) + \dots$$

leading two

coefficients of alg. eq. match  $\Rightarrow$  2 fixed solutions

$$\hat{\omega}_{2L-1} = \hat{\omega}_{2L} = \infty$$

(related to  $SO(3)$  symmetry)

and  $2L-2$  poles which are not universally fixed.

Simple Solutions

$$L=2 \quad S_{1/2}(t) = \begin{pmatrix} 1 \\ i \tan(\omega t) e^{-i\omega t} \end{pmatrix} \quad \omega = \frac{2 \text{ pi}}{\cos \vartheta}$$

$$T(\omega) = i\omega + \frac{2i}{\omega} \cos \vartheta \omega^2 - \frac{1}{\omega^2} \begin{pmatrix} \cos(2\vartheta) & e^{i\omega t} \sin(2\vartheta) \\ -e^{-i\omega t} \sin(2\vartheta) & \cos(2\vartheta) \end{pmatrix}$$

$$F(\omega) = \nu(\omega) = 2 - \frac{2}{\omega^2} \cos(2\vartheta) \quad H = -\log \frac{F(\omega) F(-\omega)}{16} = -4 \log |\cos \vartheta|$$

$$\hat{v}_{1,2}(v) = 1 + \frac{\cos(2\vartheta)}{v^2} \pm \frac{2i \cos \delta}{v} \sqrt{1 + \frac{\sin^2 \vartheta}{v^2}}$$

square-root pt at  $\hat{v}_{1,2} = \mp i \sin \delta \leftarrow$  all information ( $\vartheta$ ) contained in  $\hat{v}_j$

example at  $L=3$  great circle  $F(v) = 2 + \frac{3-J^2}{v^2} \cdot \mu \in [0, \pi]$

Select case  $1 < J \leq 3$  parametric as  $J^2 = 5 - 4 \cos \mu$

branch points at

$$\hat{v}_2 = \pm \frac{e^{-i\mu}}{\sqrt{1-2e^{-i\mu}}} \quad \hat{v}_{2,3} = \pm \frac{e^{i\mu}}{\sqrt{1-2e^{i\mu}}} = \hat{v}_{4,4}^*$$

$$\hat{v}_2 = \pm \frac{e^{-i\mu}}{\sqrt{1-2e^{-i\mu}}} \quad \hat{v}_{2,3} = \pm \frac{e^{i\mu}}{\sqrt{1-2e^{i\mu}}} = \hat{v}_{4,4}^*$$

## Spectral Curve

investigate square root branch points  $\hat{u}_n + \text{neighbourhood}$   
branch point  $\hat{u}$  is where analyticity of  $\tau_{1,2}(u)$  breaks

$$\tau_{1,2}(u) = \frac{1}{2} F(\hat{u}) \pm \hat{k} \sqrt{u - \hat{u}} + O(u - \hat{u}) \quad \text{small circle}$$

Follow function  $\tau_1(v)$  around  $v = \hat{u}$   $v(\sigma) = \hat{u} + \epsilon e^{i\sigma}$

$$\tau_1(v(\sigma)) = \frac{1}{2} F(\hat{u}) + \hat{k} \sqrt{\epsilon} e^{i\sigma/2} + O(\epsilon)$$

$\tau_1(v(\sigma))$  returns to initial value after rotation of  $\sigma$  by  $4\pi$ .  
rotation by  $2\pi$ : interchanges eigenvalues  $\tau_1 \leftrightarrow \tau_2$

$$\tau_1(v(\sigma+2\pi)) = \tau_2(v(\sigma))$$

$$\{\tau_j(v(\sigma+2\pi))\} = \{\tau_j(v(\sigma))\}.$$

2 eigenvalue functions  $R_\alpha(u)$  form a two-sheeted cover of  $\bar{\mathbb{C}}$  (minus puncture at  $u=\bar{u}=0$ )

branch points are connected in pairs by branch cuts.

eigenvalue functions  $R_\alpha(u)$  as single valued functions  $f(z)$   
on a Riemann surface  $\Gamma$  non-triv. topology. as follows

for every  $z \in \Gamma$  associate a sheet  $\alpha(z)$  and  $u(z) \in \bar{\mathbb{C}}$

s.t.  $f(z) = f_{\alpha(z)}(u(z))$  and cuts are where  $\alpha(z)$   
is discontinuous

Riemann surface is a complex curve (spectral curve)

1-d submanifolds of 2-d complex space  $(u, \tau) \in \mathbb{C}^2$

$$\Gamma = \{(u, \tau) \in \bar{\mathbb{C}}^2; \det(\tau|_U - \tau) = 0\},$$

for every value of  $v$  there are two points  $z \in \Gamma$   
 provide permutation map  $z \rightarrow z^*$  of  $v(z^*) = v(z)$

$$\tau(z^*) = \frac{\det \tau(v(z))}{\tau(z)} = F(v(z)) - \tau(z).$$

Example  $l=2$

$$z_{1,2}(v) = 1 + \frac{\cos(2v)}{v^2} \pm \frac{2i \cos \delta}{v} \sqrt{1 - \frac{\sin^2 \delta}{v^2}}$$

$$\text{introduce } v(z) = \frac{1}{2} \sin \delta \cdot (z^{-1/2})$$

$$\tau(z) = \left( \frac{z^{1/2} - 2i \cot \delta}{z^{-1/2}} \right)^2, \quad z \rightarrow z^* = -z$$

$$\text{branch pt. } z_{1,2} = \mp i$$

## 4.2 Ground State and Excitations

Compare spectral curve to (perturbative) solutions:  
Ferromagnetic ground state + excitations.

Ground State

$$\vec{s}_j = \vec{e}_2$$

$$\mathcal{L}(v) = id + \frac{i}{\beta} \sigma^2 = \mathcal{L} \text{ eigenval } (v \pm i)/v$$

$\Rightarrow T(v) = \mathcal{L}(v)^L$  has eigenvalues

$$T_{1,2}(v) = \frac{(v \pm i)^L}{v^L}, \quad \text{two disconnected sheets.}$$

have no square-root singularities..  $\Rightarrow g = -1$

but normal genus at  $L$  is  $g = L-2 \gg -1$

Spectral curve is highly degenerate.

degeneracy of  $\Gamma$ . consider  $F(u)$

$$F(u) = T_1(u) + T_2(u) = \frac{(u+i)^L + (u-i)^L}{u^L} \text{ pol. deg } L$$

$$T_{1,2}(u) = \frac{1}{2} F(u) \mp \sqrt{\frac{1}{4} F(u)^2 - \frac{(u^2+1)^L}{u^{2L}}}$$

Potential branch points:  $0 = \left( \frac{(u+i)^L - (u-i)^L}{2u^L} \right)^2$

$2L-2$  double roots at  $\hat{u}_{2k-1, 2k} = \cot \frac{\pi k}{L} \quad k=1\dots L-1$

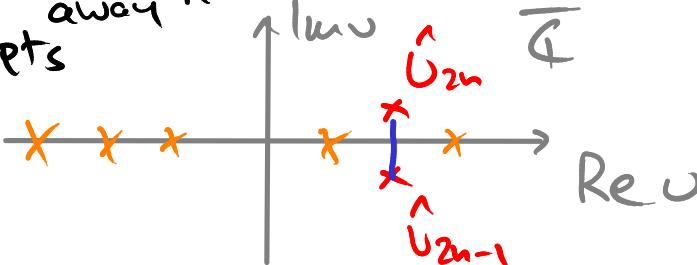
No singular behaviour of  $T_{1,2}(u)$  at  $u=\hat{u}_k$

but this signals that a higher-gens curve has degenerated  
to two configurations by moving two nearby branch pt together.

Single Excitation move two branch pts away from e.r.a.

how to change  $F(u)$  to achieve this?

Preserve Polynomial nature of  $F(u)$ .



done by  $F \rightarrow F + \delta F$  with

$$\delta F(u) = i\epsilon^2 \frac{(u+i)^L - (u-i)^L}{u^L (u - \hat{U}_{2n})}$$

- Preserves Polyn.
- zeros at  $u = \hat{U}_{2n}$
- except at  $u = \hat{U}_{2n}$

deformed eq.

$$F(\hat{U})^2 = 2 F(\hat{U}) \delta F(\hat{U}) + \dots = \frac{4 (\hat{U}^2 + 1)^L}{\hat{U}^{2L}}$$

Solutions:  $\hat{U} = \hat{U}_{2k}$  (twice) for  $k \neq n$

$$\hat{U}_{2n-1, 2n} = \hat{U}_{2n} \mp \frac{i\epsilon \sqrt{2/L}}{\sin(\pi u/L)} .$$

analyse charges of corresponding state through  $F(U)$

$$U=\infty \quad \delta F(U) = \frac{2L\epsilon^2}{U^2} + \dots \Rightarrow \text{tot ang. mo- } J \\ \Rightarrow \vec{\delta J} = -\epsilon^2 \vec{e}_2$$

energy & momentum

$$\delta H = -\frac{\delta F(+i)}{F(+i)} - \frac{\delta F(-i)}{F(-i)} = \frac{2\epsilon^2}{U_{2n}^2 + 1} = 2\epsilon^2 \sin^2 \frac{\pi n}{2}$$

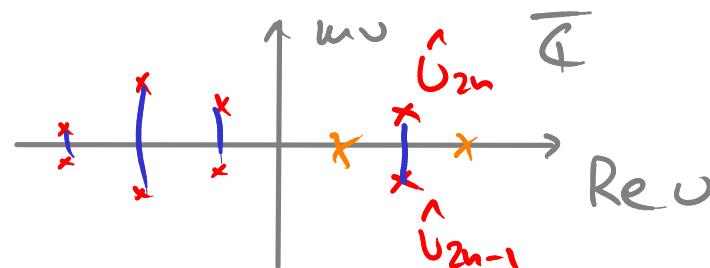
similar to excitations of ferromagn. vacuu.

$$\text{combine } J+H \Rightarrow \delta H = -2\delta J \sin^2 \frac{\pi n}{L} \text{ matches prev!}$$

use action variables

$$\delta I_n = \pm \frac{1}{2\pi} \oint_{U_{2n}} \frac{dU \tau(U)}{\sqrt{dt \tau(U)}} = \epsilon_1^2 \quad \left. \begin{aligned} \delta H &= 2\delta I_n \sin^2 \frac{\pi n}{L} + \dots \\ \vec{\delta J} &= -\delta I_n \vec{e}_2 + \dots \end{aligned} \right\} \text{agrees!} \\ \omega_n = \frac{\partial H}{\partial I_n} = 2 \sin^2 \frac{\pi n}{L}.$$

## Multiple Excitations



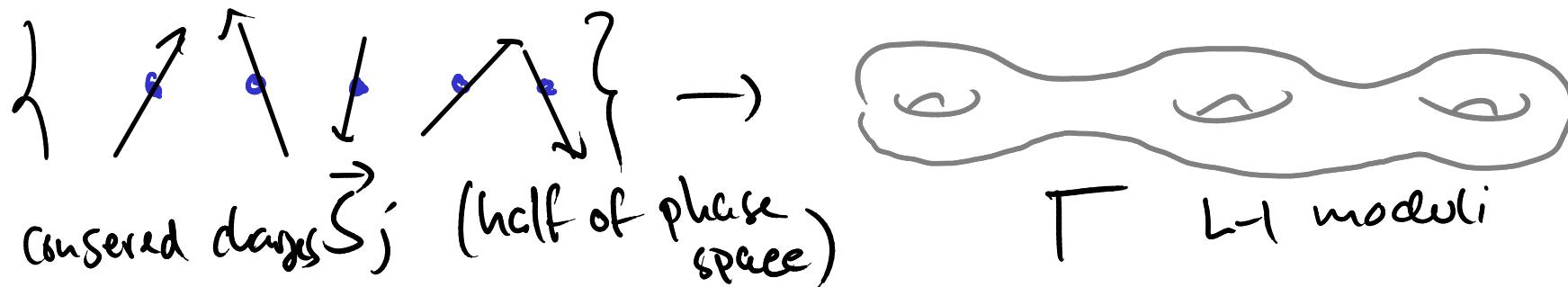
here to order  $\epsilon^2$  all deformations  
are independent  $\Rightarrow$  q.ty add up  $H = \sum_{n=1}^L I_n \cdot w_n$

leading order matches.

spectral curve provides an exact descriptor beyond linear regime.

e.g. take  $I_n$  larger, still obtain precise results including  
non-linear effects.

$L-1$  excitation modes of f.m.vac



## 4.3 Dynamical Divisor

### Singularities

Eigen vectors determined by EV eq.  $\tau_a$  eigenvalues  $a=1,2$   
 $\psi_a(u)$  corr. eigenvectors

$$\tau(u) \psi_a(u) = \tilde{\tau}_a(u) \psi_a(u)$$

Eq. has a solution  $\psi_a(u)$  for all  $\tilde{\tau}_a(u)$  for all  $u$   
 dependence on  $u$  is analytic almost everywhere  
 3 types...

1. monodromy  $\tau(u)$  has a pole singularity

$\Rightarrow \tilde{\tau}_a(u)$  has same singularity

know  $\tau(u)$  has L-fold pole at  $u=\hat{u}=0$

can remove singularity by rescaling by some pol.fn.  $u^L$   
 this does not affect eigenvectors

so no particular singularity in  $\psi_a(u)$  to be expected.

2. square-root singularities in  $\Phi_a(u)$  but not  $T(u)$  (diagonalisable).  
 contradiction from assuming  $\Phi_a(u)$  to be analytic  
 $\Rightarrow \Phi_a(u)$  has a square-root singularity at branch pt.
3. normalisation of eigenvectors is undetermined by Eo Eq.  
 may renormalise  $\Phi_a(u)$  by  $f(u)$ ; by this generate/pole remove sing.

### Branch Points

- at square-root sing. both eigenvectors degenerate  $\psi_1(\tilde{u}) = \psi_2(\tilde{u})$
- monodromy  $\tilde{T}(\tilde{u})$  is non-diagonalisable at these points.  
 $\rightarrow$  single true eigenvector  $\Psi_1(\tilde{u}^k) = \Psi_2(\tilde{u}^k)$

non-diagonalisable  $T(u)$

$$\tilde{T}(u) = \begin{pmatrix} A(u) & B(u) \\ C(u) & D(u) \end{pmatrix} \quad \begin{array}{l} A, B, C, D \text{ are analytic} \\ \text{at } u = \tilde{u}. \end{array}$$

( $T(\tilde{u})$  is not?)

eigenvalues

$$\tilde{\tau}_{1,2}(v) = \frac{1}{2} (A(v) + D(v)) \pm \sqrt{\frac{1}{4} (A(v) - D(v))^2 + B(v)C(v)}$$

branch pt are where  $\tau_1 = \tau_2$ , radicand = 0

expand at  $v=0$   $\tau(v) = \tau(0) \pm \hat{k} \sqrt{v - \hat{v}} + \dots$

$$\hat{k} = \sqrt{\frac{1}{2} (\hat{A} - \hat{D}) (\hat{A}' - \hat{D}')} + \hat{B} \hat{C}' - \hat{C} \hat{B}'$$

assume  $T(\hat{v})$  to be diagonalisable: two eigenval.  $\tau_1 = \tau_2$

$$\Rightarrow T(\hat{v}) = \tau_{1,2} \cdot \text{id} \Rightarrow \hat{A} = \hat{D}, \quad \hat{B} = \hat{C} = 0$$

$\Rightarrow \hat{k} = 0 \Rightarrow$  no square root branch point.

consider behaviour of eigenvectors at  $v=\hat{v}$

$$\varphi_a(v) = \begin{pmatrix} -B(v) \\ A(v) - \tau_a(v) \end{pmatrix}$$

Beneficial for formulating  $\psi(z)$  as a function on  $\Gamma$

$$\psi_1(\hat{v}) = \psi_2(v)$$

namely  $\varphi(z) = \psi_{\alpha(z)}(v(z))$  is analytic on  $\Gamma$   
at  $v = \hat{v}$

$$EV \text{ eq on } \Gamma \quad T(v(z)) \psi(z) = T|z| \psi(z)$$

$\varphi(z), \psi(z)$  are analytic on  $\Gamma$

example chain with  $L=2$

$$\psi(z) = \left( ie^{\frac{1}{i\omega t}} z \right)$$

## Dynamical Divisor

scaling of  $\psi(z)$  is not determined. where are singularities?

$$\psi(z) \equiv \lambda(z) \varphi(z)$$

Therefore we normalise  $\psi(z)$  in some particular way our choice

e.g.  $v_r \cdot \psi(z) \stackrel{!}{=} 1$  for some vector  $v_r$ .

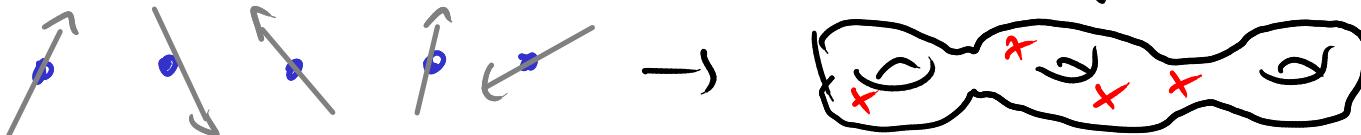
for choice  $v_r = (1 \ 0)$   $\Rightarrow \psi(z) = (\begin{smallmatrix} 1 \\ \zeta(z) \end{smallmatrix})$  stereographic projection.

reduces information in  $\psi(z)$  to a function  $\zeta(z)$

well-defined (but dependent on  $v_r$ ) set of poles  $\{\tilde{z}_k\}$

this set encodes all dynamical data of state

$\Rightarrow \{\tilde{z}_k\}$  dynamical divisor for state (set of marked points on  $\Gamma$ )



Alternative picture for  $\{\tilde{z}_n\}$ :

$\psi$  is map  $\Gamma \rightarrow \mathbb{CP}^1$  (rather than  $\mathbb{C}^2$ )

namely:  $\psi$  is defined up to scaling,  $\psi$  describes direction

$\tilde{z}_n$  are poles of  $I(z)$  but these originate from normalisation

$$V_r \cdot \psi(z) = 1 \quad \tilde{z}_n \text{ is where } \psi(z) \sim V_r^{-1}$$

Divisor consists of all points  $\tilde{z}_n$  where  $\psi(\tilde{z}_n)$  takes a specific direction.

Claim:  $\{\tilde{z}_n\}$  consists of  $g+1$  points on  $\Gamma$   $\psi \sim \left( \begin{matrix} 1 \\ g \end{matrix} \right)$   
where  $g$  is genus of  $\Gamma$ .

Define function  $f(\omega) := (\psi_1(\omega)^T \in \psi_2(\omega))^2 = (\gamma_1(\omega) - \gamma_2(\omega))^2$

1.  $f(u)$  is a meromorphic function of  $u \in \overline{\mathbb{C}}$ 
  - constant of  $z!$
  - interchange two eigenvalues/vectors  $\psi_1 \leftrightarrow \psi_2$   
 $f(u)$  remains the same  $\Rightarrow$  also analytic here.
2. zeros of  $f(u)$  are branch points.
  - note  $f(u) = 0$  if two vectors are collinear at branch pt.  $\Rightarrow f(u) \neq 0$
  - if  $T(u)$  is diagonalisable (generic  $u$ )  $\Rightarrow$  two eigenvectors span  $\mathbb{C}^2$   
 further branch point contributes single zero for  $f(u)$ .

for a curve  $\Gamma$  of genus  $g$  two sheets are connected by  
 $g+1$  branch cuts  $\Rightarrow 2g+2$  branch points.
3. meromorphic fn.  $f(u)$  on compact  $\overline{\mathbb{C}}$  has as many poles as zeros.  
 $2(g+1)$  poles. all poles are double by construction  $f(u) = (...)^2$   
 double pole due to either  $\mathfrak{J}_1(u)$  or  $\mathfrak{J}_2(u)$  (stable)  $\Rightarrow$   $g+1$  poles in  $\mathfrak{J}(2)$ .

example  $L=2$  state  $\nu_r = (1, -1/\varsigma_r)$   $\varsigma_r \in \bar{\mathbb{C}}$ .

normalize  $\psi$  st.  $\nu_r \cdot \psi = \psi_1 - \psi_2 / \varsigma_r = 1$

$$\psi(z) = \frac{1}{1 - i \varsigma_r e^{-i\omega t}} z \begin{pmatrix} 1 \\ i \bar{e}^{i\omega t} z \end{pmatrix}$$

pole at  $\tilde{z}(t) = -i \varsigma_r e^{i\omega t}$  (rotates with  $\omega$ )  
on  $\Gamma = \bar{\mathbb{C}}$

## Evolution

$\{z_k\}$  describes truly dynamical state of state

set moves around on  $\Gamma$  in well-prescribed way

$$\frac{dT}{dt} = [M, T] \Rightarrow \frac{d\psi}{dt} = M\psi + \lambda\psi \quad \begin{matrix} \leftarrow \text{normalization} \\ \text{abs + progress} \end{matrix}$$

keep  $v_r \cdot \psi = 1$  solve for  $\lambda$

$$\frac{d}{dt}\psi(z) = M(z)\psi(z) - (v_r \cdot M(z)\psi(z)) \cdot \psi(z)$$

non-linear, but nevertheless has solution.

(consider eq. near a pole  $\tilde{z}$  .. double poles on both sides: cancel!)

$$\frac{d\tilde{z}}{dt} = - \underset{z=\tilde{z}}{\operatorname{res}} (v_r \cdot M(z)\psi(z))$$

Example:

$$M(\nu) \equiv \frac{1}{\nu^2 + 1} \frac{1}{\cos \vartheta} \begin{pmatrix} i & \nu e^{i\nu t} \sin \vartheta \\ -\nu e^{-i\nu t} \sin \vartheta & -i \end{pmatrix}$$

EV evolution

$$\frac{d}{dt} \Psi + \lambda_1 \Psi = \frac{2}{\cos \vartheta} \begin{pmatrix} 0 \\ z e^{-i\nu t} \end{pmatrix} = M\Psi + \lambda_2 \Psi$$

Verify using solution  $\tilde{\Psi} = -i \zeta_r e^{i\nu t}$

$$\underset{z=\tilde{\Psi}}{\text{res}} \Psi(z) = \tilde{\Psi} \begin{pmatrix} 1 \\ \zeta_r \end{pmatrix}$$

$$(1 - \zeta_r^{-1}) M(\nu) \begin{pmatrix} 1 \\ \zeta_r \end{pmatrix} = \frac{2i}{\cos \vartheta} \frac{\nu \nu(\tilde{\Psi}) + 1}{\nu^2 + 1}$$

$$\Rightarrow \frac{d\tilde{\Psi}}{dt} = i\nu \tilde{\Psi} = \frac{2i}{\cos \vartheta} \tilde{\Psi} \quad \text{holds for actual ang. vel. } \omega = 2/\cos \vartheta$$

## Symmetry

System has  $SO(3)$  rotation symmetry and cons. charge  $\vec{J}$

lowers the typical genus of curve from  $g=L-1 \rightarrow g=L-2$

because pt  $v=\infty$  related to symmetry is double pt &  $\Gamma$

means that direction  $\vec{J}$  is not encoded in  $\Gamma$ ,

not in divisor

review expansion at  $v=\infty$

$$T(v) = \text{id} + \sum_i \vec{J} \cdot \vec{\sigma}_i + \dots$$

at  $v=\infty$  eigenvectors of  $T(w)$  are not fixed by EU eq.  
because  $T(\infty) = \text{id}$ . nevertheless can consider  $v \rightarrow \infty$

SUPPOSE  $U(z) = \frac{c}{z - z_0} + \dots$  on  $\Gamma$

$$J = |\vec{J}|$$

then  $T(z) = 1 \pm \frac{iJ}{c}(z - z_0) + \dots$

Eigenvectors  $\psi_{1,2}(z)$  as  $z \rightarrow z_0 / z_0^*$

$$(\vec{J} \cdot \vec{\sigma}) \psi(z_0) = \pm J \psi(z_0)$$

$$(\vec{J} \cdot \vec{\sigma}) \psi(z_0^*) = \mp J \psi(z_0^*)$$

## 4.4 Construction of Solutions

### Spectral Curve

construct  $\pi(z)$  on Riemann surface  $\Gamma$

$$\pi(z)^2 - F(\nu(z))\pi(z) + \det T(\nu(z)) = 0$$

$F(\nu)$  is a polynomial of deg.  $L$  in  $1/\nu$

leading terms  $F(\nu) = 2 + 0/\nu + \dots$   $L-1$  d.o.f.

$$\det T(\nu) = (1 + \nu z)^L$$

alg. eq. describes  $2L-2$  branch pt  $\Rightarrow L-1$  cuts, genus  $\overset{g=}{L-2}$   
 has  $L-1$  indep. moduli  
 correspond to  $L-1$  action variables

## Dynamical Divisor

assume normalisation  $\psi(z) = \begin{pmatrix} 1 \\ \zeta(z) \end{pmatrix}$

as a meromorphic function of degree  $g+1$  (Poles)

Riemann-Roch theorem  $\Rightarrow$   $3+g$  d.o.f. in choosing  $\psi(z)$

( $g+1$  poles, 1 scaling, 1 shift)

$\{\tilde{z}_k\}$   $\underbrace{\text{direction of } \vec{J}/J}$

## Reconstruct

$$T(\psi(z)) = \gamma(z) \frac{\psi(z)\psi(z^*)^\top \in}{+\bar{(z^*)^\top \in} \psi(z)} + \gamma(z^*) \frac{\psi(z^*)\psi(z)^\top \in}{\psi(z)^\top \in \psi(z^*)}.$$

reconstruct state  $\vec{x}_k$  from  $T(d)$



Consider d.o.f. curve generically has  $g = L - 2$

eigen vector has  $g + 3 = L + 1$  d.o.f.

$\Gamma$  has  $L - 1$  dof from  $F(u)$   
 altogether:  $2L$  d.o.f.  $\simeq$  dim of phase space  $S^2$  for each site.